

MATHEMATICS 201-NYC-05

Vectors and Matrices

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Fall 2007

Systems of Linear Equations with Maple

As with matrices, we start by loading the *LinearAlgebra* package.

```
> with(LinearAlgebra);
```

Let us consider the following system of linear equations $AX = b$.

$$3x + 3y + 2z = 3$$

$$4x - 2y + 5z = -15$$

$$2x - y - z = 3$$

We will see five different ways to solve this system of linear equations with Maple, namely *directly*, using *Gaussian elimination*, *Gauss-Jordan method*, the *inverse* and with *Cramer's Rule*.

Solving Directly

We can solve our system of linear equations directly using the `solve()` command.

```
> solve({ 3*x+3*y+2*z=3, 4*x-2*y+5*z=-15, 2*x-y-z=3 }, {x,y,z});
```

Note that this method works for any kind of equations, not just systems of linear equations.

There is an other way to solve this using the `LinearSolve()` command from the *LinearAlgebra* package.

We begin by defining the matrix of coefficients A along with the constant matrix b .

```
> A:=Matrix([[3,3,2],[4,-2,5],[2,-1,-1]]);
```

```
> b:=Matrix([[-3],[-15],[3]]);
```

Then, the solution to our system of linear equations is:

```
> LinearSolve(A,b);
```

Gaussian Elimination

The first thing we need to do is find the augmented matrix. We can either rewrite the matrix, or, since we already defined A and b , form a new matrix with them.

```
> C:=Matrix([A,b]);
```

Now we can reduce our matrix using the `GaussianElimination()` command from the *LinearAlgebra* package.

```
> G:=GaussianElimination(C);
```

Note: Maple does not give the matrix in row-echelon form since it does not have leading ones.

The solution is obtained with the `BackwardSubstitute()` command.

```
> BackwardSubstitute(G);
```

Reducing the Matrix Row by Row

Instead of using the `GaussianElimination()` command, we can obtain the reduced matrix by transforming the augmented matrix through the use of elementary row operations.

The command for elementary row operations is `RowOperation`, where you can use the option `inplace=true` if you want to overwrite the matrix, so as not to have to rename it everytime.

1. `RowOperation(A, [ri, rj], m)` $R_i \rightarrow R_i + mR_j$

2. `RowOperation(A,ri,k)` $R_i \rightarrow kR_i$
3. `RowOperation(A,[ri,rj])` $R_i \leftrightarrow R_j$

Let us reduce our augmented matrix C with these elementary row operations.

Let us start with $R_1 \rightarrow \frac{1}{3}R_1$ to make a leading 1.

> `RowOperation(C,1,1/3,inplace=true);`

and make a zeros under the leading 1, with $R_2 \rightarrow R_2 - 4R_1$ and $R_3 \rightarrow R_3 - 2R_1$

> `RowOperation(C,[2,1],-4,inplace=true);`

> `RowOperation(C,[3,1],-2,inplace=true);`

Making a leading one where the -6 is with $R_2 \rightarrow -\frac{1}{6}R_2$

> `RowOperation(C,2,-1/6,inplace=true);`

and a zero under that new leading one $R_3 \rightarrow R_3 + 3R_2$

> `RowOperation(C,[3,2],3,inplace=true);`

Lastly, making a leading one where the $-\frac{7}{2}$ with $R_3 \rightarrow -\frac{2}{7}R_3$

> `RowOperation(C,3,-2/7,inplace=true);`

Which gives us the row-echelon form for our augmented matrix.

Gauss-Jordan Method

The Gauss-Jordan method works the same way for Gaussian elimination, except that we use the command `ReducedRowEchelonForm()` from the *LinearAlgebra* package.

> `ReducedRowEchelonForm(C);`

This is probably the best method to use as it gives us a matrix where the solution stands out.

Using the Inverse

In solving the system $AX = b$, we can solve for X by finding the inverse of A , if A is invertible, then multiplying it by b . That is, $X = A^{-1}b$.

> `Multiply(MatrixInverse(A),b);`

Note that this method will only work if our system has a unique solution.

Cramer's Rule

To use Cramer's rule, we need to find the matrices $A(1)$, $A(2)$ and $A(3)$, where the matrix $A(j)$ is the matrix A with the j^{th} column replaced by the b . This can be done as follows.

> `A1 := Matrix([b, Column(A,2), Column(A,3)]);`

> `A2 := Matrix([Column(A,1), b, Column(A,3)]);`

> `A3 := Matrix([Column(A,1), Column(A,2), b]);`

With these matrices, the solution is obtained with $\frac{\det(A(j))}{\det(A)}$.

> `Determinant(A1)/Determinant(A);`

`Determinant(A2)/Determinant(A);`

`Determinant(A3)/Determinant(A);`

Maple Tutor

Maple has a number of built-in tutors, such as Gaussian elimination, that you can explore. Go to TOOLS – TUTORs – LINEAR ALGEBRA and pick the tutor you wish to try.